



AUTOWARE Open Source Autonomous Kit



- Open source navigation
- ROS structure

- Supporting DEMO
- Ready to use



The Open Source Autonomous Kit (Localization kit for research and development) AgileX Autoware is the first fully integrated, Autonomous Driving Research and Development kit. Utilizing 3D Slam localization technology, Autoware is suitable for all driving environments including on and off-road environments.

Autoware is an open-sourced development kit built ROS (Robot Operating System) allowing you to easily integrate existing libraries or new payloads and sensors.



Autoware Includes	Table of Configuration List
Intel i7-9700 CPU	8 cores 8 threads 3.0GHz
	Max memory size 32GB
	16 Channel, 905nm wave lenght,
Multi line lidar	Accuracy +-2cm(typical),
Robosense RS-LiDAR-16	Measurement range 20cm to 150m
Display Module	(on 20% reflectivity target), data rate 320,000 pts/s
	Liquid crystal display screen
	mini-hdmi to hdmi wire
	USB to Type-C wire
	USB-to-CAN module
Communication	24V to 12V 24V to 19V
Power Module	Interchanger
Communication Module	HUNTER
Compatible products	HUNTER 2.0
	SCOUT 2.0
	BUNKER

^{*} GPS module is not included in the standard package

FEATURE	
Wire controlling of the vehicle introduction, control the vehicle by ROS	
Utilize 3D point cloud for localization and Navigation	
Path planning with obstacle avoidance.	
Parking – Forward and Reverse	
Lane Changes	
Edit vector maps (Lane lines, zebra crossings, curbs, etc.)	



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