

## Operate with Ease

Spot's vision system makes it easy to navigate around objects and over rough terrain. Control the robot from afar using an intuitive tablet application and built-in stereo cameras. Spot can also be teleoperated via Scout desktop software.

## Automate Data Collection

Program repeatable autonomous missions to gather consistent data. Flexible autonomy allows Spot to adjust to changes on its programmed path as desired. Missions can be launched from the Spot Dock for remote operations.

## Customize for Your Needs

Spot can carry up to 14 kg ( 30 lbs ) of sensing equipment. Our diverse payload ecosystem is ready for a variety of applications, from thermal and acoustic inspections to laser scanning and site progress monitoring.

## Learn with Training and Support

We make it easy to get started with Spot. Our Support Center features a comprehensive collection of knowledge articles and discussion groups, product training options are available, and in addition to our one-year limited warranty, we offer premium service and support through a Spot CARE subscription.

## Industries



Manufacturing
Set Spot up to do autonomous inspection rounds or use the robot to create digital twins of a plant in advance of rework.


## Construction

Inspect progress on construction sites, create digital twins, and compare as-built conditions to Building Information Modeling (BIM) autonomously with Spot.

## Power \& Utilities

Create autonomous routes or drive the robot to remotely perform inspections in electrified or radiation dense areas.


## Mining

Create routine tunnel inspection routes and attach additional payloads to take measurements and ensure safe working conditions.

## Oil and Gas

Create autonomous
routes or drive the robot to remotely inspect facilities and improve site awareness of plant operations.

## Public Safety

Drive Spot remotely to get eyes on dangerous situations and inspect hazardous packages from afar.

## Specifications

## Base Robot

DIMENSIONS
Length $=1100 \mathrm{~mm}$ (43.3 in)
Width $=500 \mathrm{~mm}$ ( 19.7 in )
Height (Sitting) $=191 \mathrm{~mm}$ ( 7.5 in )
Default Height (Walking) =
610 mm (24.0 in)
Max Height (Walking) =
700 mm (27.6 in)
Min Height (Walking) =
520 mm (20.5 in)
Net Mass/Weight (Spot with
battery) $=32.7 \mathrm{~kg}$ ( 72.1 lbs )

## LOCOMOTION

Max Speed $=1.6 \mathrm{~m} / \mathrm{s}$
Max Slope $= \pm 30^{\circ}$
Max Step Height = 300 mm (11.8 in)

## Battery

Battery Capacity = 564 Wh
Average Runtime* $=90 \mathrm{mins}$
Standby Time $=180 \mathrm{mins}$
Recharge Time $=60 \mathrm{mins}$

TERRAIN SENSING
Horizontal Field of View $=360^{\circ}$
Range $=4 \mathrm{~m}(13 \mathrm{ft})$
Lighting = $>2$ Lux
Collision avoidance $=$
maintains set distance from
stationary obstacles
CONNECTIVITY
$\mathbf{W i F i}=2.4 \mathrm{GHz} / 5 \mathrm{GHz} \mathrm{b} / \mathrm{g} / \mathrm{n}$
Ethernet
ENVIRONMENT
Ingress Protection = IP54
Operating Temp. $=-20^{\circ} \mathrm{C}$ to $45^{\circ} \mathrm{C}$
*Runtime may vary depending on payloads and environmental factors
Length $=324 \mathrm{~mm}$ ( 12.8 in )
Width $=168 \mathrm{~mm}(6.6 \mathrm{in})$
Height $=93 \mathrm{~mm}(3.7 \mathrm{in})$
Mass/Weight = 5.2 kg ( 11.5 lbs )

## Charger

Input Voltage $=100-240 \mathrm{VAC}$
50/60Hz 8A Max
Output = 35-58.2 VDC, 12A Max
Length $=380 \mathrm{~mm}$ (15.0 in)
Width $=315 \mathrm{~mm}$ ( 12.4 in)
Height $=178 \mathrm{~mm}$ ( 7.0 in )
Mass/Weight $=7.5 \mathrm{~kg}(16.5 \mathrm{lbs})$
Operating Temp. $=0^{\circ} \mathrm{C}$ to $45^{\circ} \mathrm{C}$

## Tablet

Height $=127 \mathrm{~mm}(5.0 \mathrm{in})$
Width $=214 \mathrm{~mm}(8.4 \mathrm{in})$
Depth $=10 \mathrm{~mm}$ ( 0.4 in)
Weight $=426 \mathrm{~g}(0.9 \mathrm{lbs})$
Touch Screen Size = 8" diagonal
Resolution = 1920x1200
Ingress Protection = IP65

Joystick add-on available

## Payload Mounting

Max Weight $=14 \mathrm{~kg}(30.9 \mathrm{lbs})$
Mounting Area $=850 \mathrm{~mm}(\mathrm{~L}) \times 240$
mm (W) $\times 270 \mathrm{~mm}$ (H)
Mounting Interface $=\mathrm{M} 5 \mathrm{~T}$-slot rails
Connector $=$ DB25 (2 ports)

Power Supply = Unregulated DC $35-58.8 \mathrm{~V}, 150 \mathrm{~W}$ per port
Integration = Available software API and hardware interface control document

## Spot Dock

DIMENSIONS
Length $=1140 \mathrm{~mm}$ (44.9 in)
Width $=414 \mathrm{~mm}$ ( 16.3 in)
Height $=403 \mathrm{~mm}$ ( 15.9 in )
Mass/Weight $=22.9 \mathrm{~kg}(50.5 \mathrm{lbs})$

POWER
Input = 90-277 VAC
Output $=58 \mathrm{~V}$ at 12 A
Charge Time $=2-3.5$ hours**
**Charge time varies based on table below

| Ambient Temp. | $\mathbf{8 0 \%}$ charge | $\mathbf{1 0 0 \%}$ charge |
| :--- | :--- | :--- |
| $\mathbf{2 5}{ }^{\circ} \mathrm{C}$ | 50 min | 2 hrs |
| $\mathbf{3 5 ^ { \circ } \mathrm { C }}$ | 2.5 hrs | 3.5 hrs |

ENVIRONMENT
Operating Temp. $=0^{\circ} \mathrm{C}$ to $35^{\circ} \mathrm{C}$
Lighting = Ambient light required
Mounting = Bolt/tie down
locations provided

CONNECTIVITY
Gigabit Ethernet passthrough to robot

CERTIFICATIONS
cTUVus Certified to UL 1564
and CSA C22.2 No. 107.2

## Safety and Compliance, United States

Designed according to ISO 12100 for risk assessment and reduction methodology and IEC 60204-1 for electrical safety. See Information for Use for further details on intended uses.

## EMC: FCC Part 15B

Radio equipment: Incorporates a FCC Part 68 Certified radio system Laser product $=$ Class 1 eye-safe per IEC 60825-1:2007 \& 2014

## Travel Cases

## ROBOT CASE

Includes robot and tablet
Length $=927 \mathrm{~mm}(36.5 \mathrm{in})$
Width $=546 \mathrm{~mm}$ ( 21.5 in )
Height $=464 \mathrm{~mm}$ ( 18.25 in )
Net Mass/Weight =
47.6 kg ( 105 lbs )

## POWER CASE

Includes two batteries and charger
Length $=810 \mathrm{~mm}$ (32 in)
Width $=530 \mathrm{~mm}(21 \mathrm{in})$
Height $=300 \mathrm{~mm}$ (12 in)
Net Mass/Weight =
28 kg (61 lbs)

## Contact

